The free energy principle and the internal model principle A guide for the study of agents?

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Outline

- The free energy principle vs. active inference *
- Agency and alignment *
- The internal model principle *
- Viability theory •



The free energy principle

- A foundational theory of agents, (living) systems, "things"
- A thing is a "thing" if and only if it minimises free energy
- Markov blankets as a like a "veil" that separates internal from external states





Active inference

- Assumes POMPDs/state-space models structure (~ RL setup)
- Provides an alternative cost function (expected free energy)
- …ideally one that is derived from the FEP,
 but it can stand without it









merative models for discrete states and outcomes Unner left nanel. These equations specify the generative model A generative model is



The FEP 1.01 - as of early 2021

The FEP targets:

- systems which can be modelled as random dynamical systems with 1.
- a **unique steady-state distribution** (= weak mixing for recurrent but a-periodic Markov chains), 2.
- 3. equally valid alternatives), into orthogonal curl-free and divergence-free flows of a quasi-potential,
- 4. given the blanket (variables), based on a some selection of either internal or external "states" (the process is complementary),
- 5.
- 6. issues) to try and ensure that internal variables *model* in some non-trivial sense external ones,
- 7. descent on variational free energy ("Approximate Bayesian inference lemma").

whose vector field can be decomposed (via the Helmholtz-Hodge(+ Ao?) decomposition), uniquely and in a special way (= there's a number of

such that the set of random variables at steady-state (the stochastic process is effectively studied at steady-state) can be partitioned into internal, external and blanket "states" via an assumption (this is not an implication) of conditional independence between internal and external variables

under the additional assumption (a conjecture as seen in Friston et al. 2021, "Stochastic chaos and markov blankets") of "sparse coupling" that allows mapping of steady-state independencies to independencies on dynamical components, i.e., orthogonal curl-free and divergence-free flows,

and with a conditional synchronisation map assumed to connect the most likely internal and external states (see Aguilera et al. 2021 for possible

such systems can be said to contain a partition of internal states that appear to perform inference on a partition of external states via a gradient



AI Alignment

Biased data, algorithms, etc. for learning models (Intersections, bifurcations, dead ends for) Black-box models, agency, human feedback, reward hacking, goal emergence, ...

Super-human AIs trying to kill us





Alignment and agency

Agents: goal-directed autonomous systems that interact with, but are fundamentally distinct from, their environments

- Keywords for alignment research: goals and <u>autonomy</u>
 - Systems with misaligned goals are often not great
 - Autonomous systems with misaligned goals are can be scary
- My interest here: agency (not necessarily having to do with human-centric notions of agency)

≡ AF	Q
Q agency	
POSTS COMMENTS TAGS AND WIKI SEQUENCES USERS	
29 results	
Agency Raemon 2y . There is no computer program so persuasive that you can run it on a rock. This second book is about agency, the ability to take action in the world	
Alignment & Agency Raemon 1y	· · · ·
Partial Agency abramdemski 4y Here, I try to disassemble my concept of <mark>agency</mark> . Important background which isn't quite part of the sequence: * Selection vs Control	
Embedded Agency abramdemski 5y	o o - n
This is a sequence by Scott Garrabrant and Abram Demski on one current way of thinking about alignment: Embedded <mark>Agency</mark> .	
Agency: What it is and why it matters Daniel Kokotajlo 2y	
/optimality-is-the-tiger-and- <mark>agents</mark> -are-its-teeth and	
https://www.lesswrong.com/posts/pdJQYxCy29d7qYZxG/ <mark>agency</mark> -and-coherence	
Stuff I found online the gears to ascension 8mo	
A series of posts of stuff I found online that didn't seem well enough known in the inter- <mark>agency</mark> safety/ai safety community.	
Towards Causal Foundations of Safe AGI tom4everitt 4mo	- COVEN-
This sequence will give our take on how causality underpins many critical aspects of safe AGI, including <mark>agency</mark> , incentives	LE.
Abstraction 2020 johnswentworth 4y	
Research toward a theory of abstraction suitable for embedded <mark>agency</mark> . Key background concepts: * Causal DAGs with symmetry as a model	





Alignment and FEP/active inference

Active-inference-style

Assume agency

. . .

Example problems:

- Can goals differ from pre-assigned ones? Probably, see e.g., https://arxiv.org/abs/1710.11029 (funnily enough, related to FEP)
- Alignment of inference / learning algorithms (see paper above)
- Interactions with other agents (humans or other kinds)

FEP-style

...

Define agency

Example problems:

- Agent/non-agent distinction? (In the <u>AI Alignment</u> <u>community</u>)
- Theories of agency
- Can non-agents become agents over time?
- Can non-agentic *parts compose* to become agents?
- How do agents develop their own goals?
- + everything on the left



FEP-style alignment

- Tl;dr: agents perform inference (~ model?) their environment *
- Inspirations: *

. . .

- Cybernetics (good regulator "theorem", law of requisite variety) *
- Control theory (internal model principle) *





Internal model principle

- Like GR"T", but for <u>dynamical systems</u>, and actually * does what it says (under several assumptions)
- * ~~ to control a system (plant/body + environment) a controller/brain contains a model of (parts of) the environment when at equilibrium / the goal / control is achieved

Alignment *

- AI systems that achieve goals do so by modelling their environment (don't take it for granted!)
- Systems scientists / control engineers regularly deal with control of black boxes (alignment vs control?)
- Behavioural approaches to control (~ look at control in terms of relations between systems/how the behave)

Agent 3 Brain Body Environment 4 :0



Internal model principle as a "mini" FEP

Fully observable environment





Partially observable environment





WIP: From the IMP to Bayesian inference

Bayes theorem as a consistency equation...



Theorem 2.1 [Bayes' theorem]

stochastic map. Then there exists a stochastic map $Y \xrightarrow{g} X$ such that^{*a*}

$$\begin{array}{cccc} Y & \overbrace{q} & \overbrace{q} & \overbrace{p} & X \\ \Delta_{Y} & = & & \downarrow \Delta_{X} \\ Y \times Y & \overbrace{g \times id_{Y}} X \times Y & \overbrace{id_{X} \times f} X \times X \end{array}$$

tion, g = g'.

^aThe equals sign in this diagram indicates that the diagram commutes. The notation is meant to be consistent with higher categorical notation. Namely, we think of this equality as the identity 2-cell. We will not comment on higher categorical generalizations in this paper.

Advantages:

 S_E

 ψ

 S_C^*

discrete time -

 γ_E

 γ^*_C

- no measure theory (possibilistic setup, see next slide)
- nice (I think) graphical language
- straightforward to abstract (=/= generalise)

 S_C^*

recovering FEP (not actinf) from abstraction of this idea

Let X and Y be finite sets, let $\{\bullet\} \xrightarrow{p} X$ be a probability measure, and let $X \xrightarrow{f} Y$ be a

where $\{\bullet\} \xrightarrow{q} Y$ is given by $q := f \circ p$. Furthermore, for any other g' satisfying this condi-

... with dynamics







Viability theory

- * restrictions on which parts of a state-space they can inhabit
- Quite useful to study what systems meet the criteria to have an internal model *
- Used in biology, control, economics and other areas but rather niche *





Viability theory (maths)

- For the maths-oriented mind: dynamical systems defined using multi-valued functions ("set * valued analysis") with (co)restrictions ("viability")
- For the cat-theory-oriented mind: dynamical systems living in the Kleisly category of the * nonempty powerset monad on FinSet with with (co)restrictions (of interest is also Smooth)









2





FIGURE 0.2. Tubes satisfying the intersectability property $L(t) \cap M(t) \neq \emptyset$ and the confinement property $K(t) \subset L(t) \cap M(t)$.

